

ERRATA

Stack-based typed assembly language

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The following three figures (figures 10, 11 and 12) were not shown in the original published version of the article. These figures constitute the entire static semantics of the STAL type system.

$$\begin{array}{c}
 \boxed{\Delta \vdash \tau \quad \Delta \vdash \sigma \quad \vdash \Psi \quad \Delta \vdash \Gamma} \\
 \text{(type)} \frac{}{\Delta \vdash \tau} \text{ (fv}(\tau) \subseteq \Delta) \quad \text{(stype)} \frac{}{\Delta \vdash \sigma} \text{ (fv}(\sigma) \subseteq \Delta) \\
 \text{(htype)} \frac{\cdot \vdash \tau_1 \quad \dots \quad \cdot \vdash \tau_n}{\vdash \{\ell_1:\tau_1, \dots, \ell_n:\tau_n\}} \quad \text{(rftype)} \frac{\Delta \vdash \sigma \quad \Delta \vdash \tau_1 \quad \dots \quad \Delta \vdash \tau_n}{\Delta \vdash \{\text{sp}:\sigma, r_1:\tau_1, \dots, r_n:\tau_n\}} \\
 \boxed{\Delta \vdash \sigma_1 = \sigma_2} \\
 \text{(seq-refl)} \frac{\Delta \vdash \sigma}{\Delta \vdash \sigma = \sigma} \quad \text{(seq-sym)} \frac{\Delta \vdash \sigma_2 = \sigma_1}{\Delta \vdash \sigma_1 = \sigma_2} \\
 \text{(seq-trans)} \frac{\Delta \vdash \sigma_1 = \sigma_2 \quad \Delta \vdash \sigma_2 = \sigma_3}{\Delta \vdash \sigma_1 = \sigma_3} \\
 \text{(seq-cons)} \frac{\Delta \vdash \tau \quad \Delta \vdash \sigma_1 = \sigma_2}{\Delta \vdash \tau :: \sigma_1 = \tau :: \sigma_2} \quad \text{(seq-append)} \frac{\Delta \vdash \sigma_1 = \sigma'_1 \quad \Delta \vdash \sigma_2 = \sigma'_2}{\Delta \vdash \sigma_1 @ \sigma_2 = \sigma'_1 @ \sigma'_2} \\
 \text{(stk}\beta 1) \frac{\Delta \vdash \sigma}{\Delta \vdash \text{nil} @ \sigma = \sigma} \quad \text{(stk}\beta 2) \frac{\Delta \vdash \sigma}{\Delta \vdash \sigma @ \text{nil} = \sigma} \\
 \text{(stk}\beta 3) \frac{\Delta \vdash \tau \quad \Delta \vdash \sigma_1 \quad \Delta \vdash \sigma_2}{\Delta \vdash (\tau :: \sigma_1) @ \sigma_2 = \tau :: (\sigma_1 @ \sigma_2)} \\
 \text{(stk}\beta 4) \frac{\Delta \vdash \sigma_1 \quad \Delta \vdash \sigma_2 \quad \Delta \vdash \sigma_3}{\Delta \vdash (\sigma_1 @ \sigma_2) @ \sigma_3 = \sigma_1 @ (\sigma_2 @ \sigma_3)} \\
 \boxed{\Delta \vdash \Gamma_1 \leq \Gamma_2} \\
 \text{(rf-leq)} \frac{\Delta \vdash \tau_i \text{ (for } 1 \leq i \leq m) \quad \Delta \vdash \sigma = \sigma'}{\Delta \vdash \{\text{sp}:\sigma, r_1:\tau_1, \dots, r_m:\tau_m\} \leq \{\text{sp}:\sigma', r_1:\tau_1, \dots, r_n:\tau_n\}} \text{ (} m \geq n \text{)}
 \end{array}$$

Fig. 10. Static Semantics of STAL, Judgments for Types

$$\begin{array}{c}
\boxed{\vdash M \quad \vdash H : \Psi \quad \Psi \vdash S : \sigma \quad \Psi \vdash R : \Gamma} \\
(\text{mach}) \frac{\vdash H : \Psi \quad \Psi \vdash R : \Gamma \quad \Psi; \cdot; \Gamma \vdash I}{\vdash (H, R, I)} \\
(\text{heap}) \frac{\vdash \Psi \quad \Psi \vdash h_i : \Psi(\ell_i) \text{ hval} \quad (\text{for } 1 \leq i \leq n)}{\vdash \{\ell_1 \mapsto h_1, \dots, \ell_n \mapsto h_n\} : \Psi} \\
(\text{nil}) \frac{}{\Psi \vdash \text{nil} : \text{nil}} \quad (\text{cons}) \frac{\Psi; \cdot; \cdot \vdash w : \tau \quad \Psi \vdash S : \sigma}{\Psi \vdash w :: S : \tau :: \sigma} \quad (\text{stkeq}) \frac{\Psi \vdash S : \sigma_1 \quad \cdot \vdash \sigma_1 = \sigma_2}{\Psi \vdash S : \sigma_2} \\
(\text{regfile}) \frac{\Psi \vdash S : \sigma \quad \Psi; \cdot; \cdot \vdash w_i : \tau_i \quad (\text{for } 1 \leq i \leq n)}{\Psi \vdash \{\text{sp} \mapsto S, r_1 \mapsto w_1, \dots, r_m \mapsto w_m\} : \{\text{sp} : \sigma, r_1 : \tau_1, \dots, r_n : \tau_n\}} \quad (m \geq n) \\
\boxed{\Psi \vdash h : \tau \text{ hval} \quad \Psi; \Delta; \Gamma \vdash v : \tau} \\
(\text{tuple}) \frac{\Psi; \cdot; \cdot \vdash w_i : \tau_i}{\Psi \vdash \langle w_1, \dots, w_n \rangle : \langle \tau_1, \dots, \tau_n \rangle \text{ hval}} \quad (\text{code}) \frac{\Delta \vdash \Gamma \quad \Psi; \Delta; \Gamma \vdash I}{\Psi \vdash \text{code}[\Delta]\Gamma.I : \forall[\Delta].\Gamma \text{ hval}} \\
(\text{label}) \frac{}{\Psi; \Delta; \Gamma \vdash \ell : \Psi(\ell)} \quad (\text{int}) \frac{}{\Psi; \Delta; \Gamma \vdash i : \text{int}} \\
(\text{ns}) \frac{}{\Psi; \Delta; \Gamma \vdash \text{ns} : \top} \quad (\text{ptr}) \frac{\Delta \vdash \sigma}{\Psi; \Delta; \Gamma \vdash \text{ptr}(i) : \text{ptr}(\sigma)} \quad (|\sigma| = i) \\
(\text{reg}) \frac{}{\Psi; \Delta; \Gamma \vdash r : \Gamma(r)} \\
(\text{tapp}) \frac{\Delta \vdash \tau \quad \Psi; \Delta; \Gamma \vdash v : \forall[\alpha, \Delta']. \Gamma'}{\Psi; \Delta; \Gamma \vdash v[\tau] : \forall[\Delta']. \Gamma'[\tau/\alpha]} \quad (\text{stapp}) \frac{\Delta \vdash \sigma \quad \Psi; \Delta; \Gamma \vdash v : \forall[\rho, \Delta']. \Gamma'}{\Psi; \Delta; \Gamma \vdash v[\sigma] : \forall[\Delta']. \Gamma'[\sigma/\rho]} \\
(\text{pack}) \frac{\Delta \vdash \tau \quad \Psi; \Delta; \Gamma \vdash v : \tau'[\tau/\alpha]}{\Psi; \Delta; \Gamma \vdash \text{pack} [\tau, v] \text{ as } \exists \alpha. \tau' : \exists \alpha. \tau'} \\
\boxed{\Psi; \Delta; \Gamma \vdash I} \\
(\text{seq}) \frac{\Psi; \Delta; \Gamma \vdash \iota \Rightarrow \Delta'; \Gamma' \quad \Psi; \Delta'; \Gamma' \vdash I}{\Psi; \Delta; \Gamma \vdash \iota; I} \quad (\text{jmp}) \frac{\Delta \vdash \Gamma_1 \leq \Gamma_2 \quad \Psi; \Delta; \Gamma_1 \vdash v : \forall[\cdot]. \Gamma_2}{\Psi; \Delta; \Gamma_1 \vdash \text{jmp } v} \\
(\text{halt}) \frac{\Psi; \Delta; \Gamma \vdash r1 : \tau}{\Psi; \Delta; \Gamma \vdash \text{halt}[\tau]}
\end{array}$$

Fig. 11. STAL Static Semantics, Term Constructs except Instructions

$$\begin{array}{c}
\text{(aop)} \frac{\Psi; \Delta; \Gamma \vdash r_s : \text{int} \quad \Psi; \Delta; \Gamma \vdash v : \text{int}}{\Psi; \Delta; \Gamma \vdash \text{aop } r_d, r_s, v \Rightarrow \Delta; \Gamma \{r_d : \text{int}\}} \\
\text{(bop)} \frac{\Psi; \Delta; \Gamma_1 \vdash r : \text{int} \quad \Psi; \Delta; \Gamma_1 \vdash v : \forall[] . \Gamma_2 \quad \Delta \vdash \Gamma_1 \leq \Gamma_2}{\Psi; \Delta; \Gamma_1 \vdash \text{bop } r, v \Rightarrow \Delta; \Gamma_1} \\
\text{(ld)} \frac{\Psi; \Delta; \Gamma \vdash r_s : \langle \tau_0, \dots, \tau_{n-1} \rangle}{\Psi; \Delta; \Gamma \vdash \text{ld } r_d, r_s(i) \Rightarrow \Delta; \Gamma \{r_d : \tau_i\}} \quad (0 \leq i < n) \\
\text{(malloc)} \frac{\Psi; \Delta; \Gamma \vdash v_i : \tau_i}{\Psi; \Delta; \Gamma \vdash \text{malloc } r_d, \langle v_1, \dots, v_n \rangle \Rightarrow \Delta; \Gamma \{r_d : \langle \tau_1, \dots, \tau_n \rangle\}} \quad (1 \leq i \leq n) \\
\text{(mov)} \frac{\Psi; \Delta; \Gamma \vdash v : \tau}{\Psi; \Delta; \Gamma \vdash \text{mov } r_d, v \Rightarrow \Delta; \Gamma \{r_d : \tau\}} \\
\text{(unpack)} \frac{\Psi; \Delta; \Gamma \vdash v : \exists \alpha. \tau}{\Psi; \Delta; \Gamma \vdash \text{unpack } [\alpha, r_d], v \Rightarrow \alpha, \Delta; \Gamma \{r_d : \tau\}} \quad (\alpha \notin \Delta) \\
\text{(get-sp)} \frac{}{\Psi; \Delta; \Gamma \vdash \text{mov } r_d, \text{sp} \Rightarrow \Delta; \Gamma \{r_d : \text{ptr}(\sigma)\}} \quad (\Gamma(\text{sp}) = \sigma) \\
\text{(set-sp)} \frac{\Psi; \Delta; \Gamma \vdash r_s : \text{ptr}(\sigma_2) \quad \Delta \vdash \sigma_1 = \sigma_3 @ \sigma_2}{\Psi; \Delta; \Gamma \vdash \text{mov } \text{sp}, r_s \Rightarrow \Delta; \Gamma \{\text{sp} : \sigma_2\}} \quad (\Gamma(\text{sp}) = \sigma_1) \\
\text{(salloc)} \frac{}{\Psi; \Delta; \Gamma \vdash \text{salloc } n \Rightarrow \Delta; \Gamma \{\text{sp} : \underbrace{\tau_1 :: \dots :: \tau_n}_{n}\}} \quad (\Gamma(\text{sp}) = \sigma) \\
\text{(sfree)} \frac{\Delta \vdash \sigma_1 = \tau_0 :: \dots :: \tau_{n-1} :: \sigma_2}{\Psi; \Delta; \Gamma \vdash \text{sfree } n \Rightarrow \Delta; \Gamma \{\text{sp} : \sigma_2\}} \quad (\Gamma(\text{sp}) = \sigma_1) \\
\text{(sld1)} \frac{\Delta \vdash \sigma_1 = \tau_0 :: \dots :: \tau_i :: \sigma_2}{\Psi; \Delta; \Gamma \vdash \text{sld } r_d, \text{sp}(i) \Rightarrow \Delta; \Gamma \{r_d : \tau_i\}} \quad (\Gamma(\text{sp}) = \sigma_1 \wedge 0 \leq i) \\
\text{(sld2)} \frac{\Psi; \Delta; \Gamma \vdash r_s : \text{ptr}(\sigma_3) \quad \Delta \vdash \sigma_1 = \sigma_2 @ \sigma_3 \quad \Delta \vdash \sigma_3 = \tau_0 :: \dots :: \tau_i :: \sigma_4}{\Psi; \Delta; \Gamma \vdash \text{sld } r_d, r_s(i) \Rightarrow \Delta; \Gamma \{r_d : \tau_i\}} \quad (\Gamma(\text{sp}) = \sigma_1 \wedge 0 \leq i) \\
\text{(sst1)} \frac{\Delta \vdash \sigma_1 = \tau_0 :: \dots :: \tau_i :: \sigma_2 \quad \Psi; \Delta; \Gamma \vdash r_s : \tau}{\Psi; \Delta; \Gamma \vdash \text{sst } \text{sp}(i), r_s \Rightarrow \Delta; \Gamma \{\text{sp} : \tau_0 :: \dots :: \tau_{i-1} :: \tau :: \sigma_2\}} \quad (\Gamma(\text{sp}) = \sigma_1 \wedge 0 \leq i) \\
\text{(sst2)} \frac{\Psi; \Delta; \Gamma \vdash r_d : \text{ptr}(\sigma_3) \quad \Psi; \Delta; \Gamma \vdash r_s : \tau \quad \Delta \vdash \sigma_1 = \sigma_2 @ \sigma_3 \quad \Delta \vdash \sigma_3 = \tau_0 :: \dots :: \tau_i :: \sigma_4 \quad \Delta \vdash \sigma_5 = \tau_0 :: \dots :: \tau_{i-1} :: \tau :: \sigma_4}{\Psi; \Delta; \Gamma \vdash \text{sst } r_d(i), r_s \Rightarrow \Delta; \Gamma \{\text{sp} : \sigma_2 @ \sigma_5, r_d : \text{ptr}(\sigma_5)\}} \quad (\Gamma(\text{sp}) = \sigma_1 \wedge 0 \leq i) \\
\text{(st)} \frac{\Psi; \Delta; \Gamma \vdash r_d : \langle \tau_0, \dots, \tau_{n-1} \rangle \quad \Psi; \Delta; \Gamma \vdash r_s : \tau_i}{\Psi; \Delta; \Gamma \vdash \text{st } r_d(i), r_s \Rightarrow \Delta; \Gamma} \quad (0 \leq i < n)
\end{array}$$

Fig. 12. STAL Static Semantics, Instructions