

Appendix

Here we list the various abbreviations and integrals that enter the equation for the basic steady two-dimensional flow ((3.4)-(3.7)) and the linear stability problem ((4.6)-(4.16)).

The matrices $(A, B, D, E)_{klm}$, \hat{K}_{kl} and the non-linearities $C_{kljnm} \Psi_{ij}^{(o)} \Psi_{nm}^{(o)}$ and $F_{kljnm} \Psi_{ij}^{(o)} \hat{\theta}_{nm}^{(o)}$ that are required for the basic state are defined as follows. Summation is over all pairwise indices.

$$\begin{aligned}
 A_{klm} &= \frac{1}{\Gamma} \left\{ \alpha_1(l,m) \beta_1(k,n) + 2\Gamma^2 \alpha_2(l,m) [\beta_2(k,n) + \right. \\
 &\quad \left. + \beta_3(k,n) - \beta_4(k,n)] + \Gamma^4 \delta_{l,m} [\beta_5(k,n) + 2\beta_6(k,n) - \right. \\
 &\quad \left. - 3\beta_7(k,n) + 3\beta_8(k,n) - 3\frac{\pi}{2} c_k \delta_{n,k}] \right\}; \quad k \leq N-4 \\
 B_{klm} &= \frac{Gr}{Re} \alpha_5(l,m) \beta_9(k,n); \quad k \leq N-4 \\
 D_{klm} &= \alpha_5(m,l) \left\{ \beta_8(k,n) + \frac{\pi}{2} c_k \delta_{k,n} \right\}; \quad k \leq N-2 \\
 E_{klm} &= \frac{\Gamma}{RePr} \delta_{l,m} \left\{ \beta_{10}(k,n) + \beta_{11}(k,n) - \bar{m}^2 \frac{\pi^2}{\Gamma^2} \beta_{12}(k,n) \right\}; \quad k \leq N-2 \\
 \hat{K}_{kl} &= -\frac{4}{\Gamma^2} \delta_{k,N} \alpha_4(l)
 \end{aligned} \tag{A.1a-e}$$

The non-linear terms are given by

$$\begin{aligned}
 C_{kljnm} \Psi_{ij}^{(o)} \Psi_{nm}^{(o)} &= Re \left\{ \Gamma^2 \left[\zeta_{ljn}^{(1)} \sigma_{kjn}^{(1)} + \zeta_{ljn}^{(2)} \sigma_{kjn}^{(2)} \right] + \right. \\
 &\quad \left. + \zeta_{ljn}^{(3)} \sigma_{kjn}^{(3)} + \zeta_{ljn}^{(4)} \sigma_{kjn}^{(4)} \right\}, \\
 F_{kljnm} \Psi_{ij}^{(o)} \hat{\theta}_{nm}^{(o)} &= \xi_{ljn}^{(1)} \pi_{kjn}^{(1)} + \xi_{ljn}^{(2)} \pi_{kjn}^{(2)}
 \end{aligned} \tag{A.2a-b}$$

where

$$\begin{aligned}
\zeta_{ljn}^{(1)} &= \tau_{lmj}^{(2)} \Psi_{nm}^{(o)}, & \tau_{kjn}^{(1)} &= \Gamma_{kin}^{(3)} \Psi_{ij}^{(o)}, \\
\zeta_{ljn}^{(2)} &= \tau_{ljm}^{(2)} \Psi_{nm}^{(o)}, & \tau_{kjn}^{(2)} &= -\Gamma_{kin}^{(4)} \Psi_{ij}^{(o)}, \\
\zeta_{ljn}^{(3)} &= \tau_{ljm}^{(1)} \Psi_{nm}^{(o)}, & \tau_{kjn}^{(3)} &= \Gamma_{kin}^{(5)} \Psi_{ij}^{(o)}, \\
\zeta_{ljn}^{(4)} &= \tau_{ljm}^{(3)} \Psi_{nm}^{(o)}, & \tau_{kjn}^{(4)} &= -\Gamma_{kin}^{(6)} \Psi_{ij}^{(o)},
\end{aligned} \tag{A.3a-h}$$

and

$$\begin{aligned}
\xi_{ljn}^{(1)} &= \kappa_{ljm}^{(1)} \hat{\theta}_{nm}^{(0)}, & \pi_{kjn}^{(1)} &= -\Gamma_{kin}^{(1)} \hat{\Psi}_{ij}^{(o)}, \\
\xi_{ljn}^{(2)} &= \kappa_{ljm}^{(2)} \hat{\theta}_{nm}^{(0)}, & \pi_{kjn}^{(2)} &= \Gamma_{kin}^{(2)} \hat{\Psi}_{ij}^{(o)},
\end{aligned} \tag{A.4a-d)$$

with abbreviations

$$\left. \begin{aligned}
\Gamma_{kin}^{(1)} &= \gamma_9(k,n,i) \\
\Gamma_{kin}^{(2)} &= \gamma_9(k,i,n) + \gamma_{10}(k,i,n) \\
\Gamma_{kin}^{(3)} &= \gamma_1(k,i,n) + \gamma_6(k,i,n) + \gamma_4(k,i,n) - \\
&\quad - \gamma_7(k,i,n) + \gamma_7(k,n,i) - \gamma_8(k,i,n), \\
\Gamma_{kin}^{(4)} &= \gamma_3(k,i,n) - 3\gamma_7(k,n,i) + 3\gamma_8(k,i,n), \\
\Gamma_{kin}^{(5)} &= \gamma_2(k,i,n) + \gamma_5(k,i,n), \\
\Gamma_{kin}^{(6)} &= \gamma_2(k,n,i) - \gamma_5(k,i,n),
\end{aligned} \right\} \begin{array}{l} k \leq N-2 \\ k \leq N-4 \end{array} \\
\Gamma_{kin}^{(1)} = \Gamma_{kin}^{(2)} = 0; \quad k = N-1, \quad N \\
\Gamma_{kin}^{(3)} = \Gamma_{kin}^{(4)} = \Gamma_{kin}^{(5)} = \Gamma_{kin}^{(6)} = 0; \quad k > N-4. \tag{A.5a-h)$$

We have used the following integrals over axial basis functions ($\langle \cdot \rangle = \int_{-\frac{1}{2}}^{\frac{1}{2}} dz$ denotes the scalar product).

$$\begin{aligned}
\alpha_1(l,m) &= \langle H_l H_m^{IV} \rangle & \alpha_6(l,m) &= \langle R_l H_m^{II} \rangle \\
\alpha_2(l,m) &= \langle H_l H_m^{II} \rangle & \alpha_7(l,m) &= \langle R_l R_m^I \rangle \\
\alpha_3(l,m) &= \langle H_l R_m^I \rangle & \alpha_8(l,m) &= \langle R_l H_m^{IV} \rangle \\
\alpha_4(l) &= \langle H_l \rangle & \alpha_9(l,m) &= \langle R_l R_m^{III} \rangle \\
\alpha_5(l,m) &= \langle H_l R_m \rangle & \alpha_{10}(l,m) &= \langle R_l H_m^I \rangle \\
\tau_1(l,j,m) &= \langle H_l H_j H_m^{III} \rangle & \tau_3(l,j,m) &= \langle H_l H_j^I H_m^{II} \rangle
\end{aligned}$$

$$\begin{aligned}
\tau_2(l,j,m) &= \langle H_l H_j^I H_m \rangle \\
\kappa_1(l,j,m) &= \langle R_l H_j^I R_m \rangle & \kappa_4(l,j,m) &= \langle R_l H_j^H R_m \rangle \\
\kappa_2(l,j,m) &= \langle R_l H_j R_m^I \rangle & \kappa_5(l,j,m) &= \langle R_l H_j^I R_m^I \rangle \\
\kappa_3(l,j,m) &= \langle R_l H_j R_m^H \rangle & \eta_1(l,j,m) &= \langle R_l R_j R_m \rangle \\
\phi_1(l,j,m) &= \langle R_l H_j H_m^I \rangle & \phi_3(l,j,m) &= \langle R_l H_j^I H_m^H \rangle \\
\phi_2(l,j,m) &= \langle R_l H_j^I H_m^I \rangle & \phi_4(l,j,m) &= \langle R_l H_j H_m^H \rangle
\end{aligned} \tag{A.6a-v}$$

The superscript denotes the axial derivatives, e.g. $R_m^I = \frac{dR_m}{dz}$. Integrals involving radial basis functions are

$$\begin{aligned}
\beta_1(k,n) &= \langle T_k \rho^4 T_n \rangle & \beta_7(k,n) &= \langle T_k \rho^2 T_n^H \rangle \\
\beta_2(k,n) &= \langle T_k \rho^4 T_n^H \rangle & \beta_8(k,n) &= \langle T_k \rho T_n^I \rangle \\
\beta_3(k,n) &= \langle T_k \rho^3 T_n^I \rangle & \beta_9(k,n) &= \langle T_k \rho^4 T_n^I \rangle \\
\beta_4(k,n) &= \langle T_k \rho^2 T_n^I \rangle & \beta_{10}(k,n) &= \langle T_k \rho T_n^H \rangle \\
\beta_5(k,n) &= \langle T_k \rho^4 T_n^{IV} \rangle & \beta_{11}(k,n) &= \langle T_k T_n^I \rangle \\
\beta_6(k,n) &= \langle T_k \rho^3 T_n^{III} \rangle & \beta_{12}(k,n) &= \langle T_k \rho T_n \rangle
\end{aligned} \tag{A.7a-l}$$

and

$$\begin{aligned}
\gamma_1(k,i,n) &= \langle \rho^4 T_k T_i^I T_n^H \rangle & \gamma_6(k,i,n) &= \langle \rho^3 T_k T_i T_n^H \rangle \\
\gamma_2(k,i,n) &= \langle \rho^4 T_k T_i^I T_n \rangle & \gamma_7(k,i,n) &= \langle \rho^2 T_k T_i^I T_n \rangle \\
\gamma_3(k,i,n) &= \langle \rho^4 T_k T_i T_n^H \rangle & \gamma_8(k,i,n) &= \langle \rho T_k T_i T_n \rangle \\
\gamma_4(k,i,n) &= \langle \rho^3 T_k T_i^I T_n^I \rangle & \gamma_9(k,i,n) &= \langle \rho T_k T_i^I T_n \rangle \\
\gamma_5(k,i,n) &= \langle \rho^3 T_k T_i T_n \rangle & \gamma_{10}(k,i,n) &= \langle T_k T_i T_n \rangle
\end{aligned} \tag{A.8a-j}$$

Here $\rho = 1+x$, the superscript denotes radial derivatives, and $\langle \rangle$ is the integral with standard Chebyshev weight and normalization

$$\langle T_k T_n \rangle = \frac{\pi}{2} c_k \delta_{k,n}, \quad \text{where } c_k = \begin{cases} 2, & \text{if } k = 0 \\ 1, & \text{if } k \neq 0 \end{cases} \tag{A.9}$$

If feasible, integrals over axial functions have been calculated analytically. The remaining integrals have been computed numerically using a 3-point Gaussian integration scheme with relative accuracy of 10^{-10} . Integrals over Chebyshev functions have been calculated utilizing addition theorems and calculating derivatives in Chebyshev space.

The sub-matrices A^{ij} and B^{ij} that enter the stability equations are defined in the following, where the abbreviations $\Gamma = 2\tilde{\Gamma}$, $\rho_k = 1+x_k$ and $T_n(k) := T_n(x_k)$ (c.f. (4.18)) are used.

$$\begin{aligned}
 A^{11}(k,l,n,m) &= -\alpha_7(l,m) \frac{1}{\Gamma} \left\{ \rho_k^2 T_n^I(k) + \rho_k T_n(k) \right\} \\
 A^{12}(k,l,n,m) &= T_n(k) \left\{ \bar{m}^2 \alpha_5(m,l) - \alpha_6(l,m) \frac{\rho_k^2}{\Gamma^2} \right\} \\
 A^{13}(k,l,n,m) &= 0 \\
 A^{21}(k,l,n,m) &= \alpha_7(l,m) T_n(k) \\
 A^{22}(k,l,n,m) &= -\alpha_5(m,l) \Gamma T_n^I(k) \\
 A^{23}(k,l,n,m) &= 0 \\
 A^{31}(k,l,n,m) &= 0 \\
 A^{32}(k,l,n,m) &= 0 \\
 A^{33}(k,l,n,m) &= \delta_{l,m} T_n(k)
 \end{aligned} \tag{A.10a-i}$$

and

$$\begin{aligned}
 B^{11}(k,l,n,m) &= \Pi^{11}(k,l,n,m) + \operatorname{Re} \Psi_{ij}^{(o)} \left\{ \kappa_3(l,j,m) \right. \\
 &\quad \left[\Omega_1^{11}(k,i,n) + m^2 \pi^2 \Omega_2^{11}(k,i,n) \right] \\
 &\quad + \kappa_4(l,j,m) \Omega_3^{11}(k,i,n) \\
 &\quad \left. + \kappa_5(l,j,m) \Omega_4^{11}(k,i,n) \right\} \\
 B^{12}(k,l,n,m) &= \Pi^{12}(k,l,n,m) + \operatorname{Re} \Psi_{ij}^{(o)} \left\{ \phi_1(l,j,m) \Omega_1^{12}(k,i,n) + \right. \\
 &\quad + \phi_1(l,m,j) \Omega_2^{12}(k,i,n) + \phi_3(l,j,m) \Omega_3^{12}(k,i,n) + \\
 &\quad \left. + \phi_3(l,m,j) \Omega_4^{12}(k,i,n) + \phi_4(l,j,m) \Omega_5^{12}(k,i,n) \right\}
 \end{aligned}$$

$$B^{13}(k,l,n,m) = \bar{m}^2 \frac{Gr}{Re} \delta_{l,m} T_n(k)$$

$$\begin{aligned} B^{21}(k,l,n,m) &= \Pi^{21}(k,l,n,m) + Re\Psi_{ij}^{(o)} \left\{ \kappa_3(l,j,m) \right. \\ &\quad \left[\Omega_1^{21}(k,i,n) + m^2 \pi^2 \Omega_2^{21}(k,i,n) \right] + \kappa_4(l,j,m) \Omega_3^{21}(k,i,n) + \\ &\quad \left. + \kappa_5(l,j,m) \Omega_4^{21}(k,i,n) \right\} \end{aligned}$$

$$\begin{aligned} B^{22}(k,l,n,m) &= \Pi^{22}(k,l,n,m) + Re\Psi_{ij}^{(o)} \left\{ \phi_1(l,j,m) \Omega_1^{22}(k,i,n) + \right. \\ &\quad + \phi_1(l,m,j) \Omega_2^{22}(k,i,n) + \\ &\quad \left. + (\phi_3(l,m,j) + \phi_4(l,m,j)) \Omega_3^{22}(k,i,n) \right\} \end{aligned}$$

$$B^{23}(k,l,n,m) = -\Gamma \frac{Gr}{Re} \delta_{l,m} T_n^I(k)$$

$$B^{31}(k,l,n,m) = Re\hat{\theta}_{ij}^{(o)} \eta_1(l,j,m) \Omega_1^{31}(k,i,n)$$

$$\begin{aligned} B^{32}(k,l,n,m) &= Re \left\{ \Pi^{32}(k,l,n,m) + \right. \\ &\quad \left. + \kappa_2(l,m,j) \Omega_1^{32}(k,i,n) \hat{\theta}_{ij}^{(o)} \right\} \end{aligned}$$

$$\begin{aligned} B^{33}(k,l,n,m) &= \Pi^{33}(k,l,n,m) + Re\Psi_{ij}^{(o)} \left\{ \kappa_1(l,j,m) \right. \\ &\quad \left. \Omega_1^{33}(k,i,n) + \kappa_2(l,j,m) \Omega_2^{33}(k,i,n) \right\} \end{aligned} \quad (\text{A.11a-i})$$

In the equations for B^{ij} , the indices j,l,m run from 1 through M and i,n run from 0 through N . The index k runs from 0 through $N-2$ except for B^{21} , B^{22} , and B^{23} , where it runs from 0 through $N-3$. The abbreviations used in the above equations for B^{ij} are

$$\begin{aligned} \Pi^{11}(k,l,n,m) &= -\alpha_7(l,m) \Gamma \left[\rho_k^2 T_n^{III}(k) + 4\rho_k T_n^{II}(k) + \right. \\ &\quad \left. (\bar{m}^2 - 1) \left(\frac{T_n(k)}{\rho_k} - T_n^I(k) \right) \right] - \frac{\alpha_9(l,m)}{\Gamma} \left[\rho_k^2 T_n^I(k) + \right. \\ &\quad \left. \rho_k T_n(k) \right] \\ \Pi^{12}(k,l,n,m) &= \bar{m}^2 \alpha_5(m,l) \Gamma^2 \left[T_n^{II}(k) + \frac{T_n^I(k)}{\rho_k} - \bar{m}^2 \frac{T_n(k)}{\rho_k^2} \right] - \\ &\quad - \alpha_6(l,m) \left[\rho_k^2 T_n^{II}(k) + 3\rho_k T_n^I(k) - 2\bar{m}^2 T_n(k) \right] - \\ &\quad - \alpha_8(l,m) \frac{\rho_k^2 T_n(k)}{\Gamma^2} \end{aligned}$$

$$\begin{aligned}\Pi^{21}(k,l,n,m) &= \alpha_6(l,m)\Gamma\left[2\frac{T_n(k)}{\rho_k} - T_n^I(k)\right] + \alpha_5(m,l)\Gamma^3 \\ &\quad \left[\bar{m}^2\left(\frac{T_n^I(k)}{\rho_k^2} - \frac{2T_n(k)}{\rho_k^3}\right) - T_n^{III}(k) - \frac{T_n^{II}(k)}{\rho_k} + \frac{T_n^I(k)}{\rho_k^2}\right]\end{aligned}$$

$$\begin{aligned}\Pi^{32}(k,l,n,m) &= -\alpha_5(m,l)T_n(k) \\ \Pi^{33}(k,l,n,m) &= \frac{\Gamma^2}{Pr}\delta_{l,m}\left[T_n^{II}(k) + \frac{T_n^I(k)}{\rho_k} - \bar{m}^2\frac{T_n(k)}{\rho_k^2} - \frac{m^2\pi^2}{\Gamma^2}T_n(k)\right]\end{aligned}\quad (\text{A.12a-e})$$

and

$$\begin{aligned}\Omega_1^{11}(k,i,n) &= \bar{m}^2\Gamma^2\left(T_i^I(k) + \frac{T_i^I(k)}{\rho_k} - \frac{T_i(k)}{\rho_k^2}\right)T_n(k) \\ \Omega_2^{11}(k,i,n) &= \left(\rho_k T_i^I(k) + T_i(k)\right)\left(\rho_k T_n^I(k) + T_n(k)\right) \\ \Omega_3^{11}(k,i,n) &= \left(\rho_k T_n^{II}(k) + 3T_n^I(k) + \frac{T_n(k)}{\rho_k}\right)\rho_k T_i(k) \\ \Omega_4^{11}(k,i,n) &= \rho_k\left[T_i(k)\left(\rho_k T_n^{II}(k) + 2T_n^I(k)\right) - \rho_k T_i^I(k)\left(T_n^I(k) + \frac{T_n(k)}{\rho_k}\right)\right] \\ \Omega_1^{12}(k,i,n) &= \bar{m}^2\Gamma T_n(k)\left(T_i^I(k) + \frac{T_i(k)}{\rho_k}\right) \\ \Omega_2^{12}(k,i,n) &= \bar{m}^2\Gamma\left[T_n(k)\left(T_i^I(k) + \frac{T_i(k)}{\rho_k}\right) - T_i(k)T_n^I(k)\right] \\ \Omega_3^{12}(k,i,n) &= \frac{\rho_k^2}{\Gamma}\left[T_i(k)T_n^I(k) - T_i^I(k)T_n(k) + \frac{T_i(k)T_n(k)}{\rho_k}\right] \\ \Omega_4^{12}(k,i,n) &= \frac{\rho_k}{\Gamma}T_i(k)\left[\rho_k T_n^I(k) + 2T_n(k)\right] \\ \Omega_5^{12}(k,i,n) &= -\frac{T_n(k)}{\Gamma}\rho_k^2\left[T_i^I(k) + \frac{T_i(k)}{\rho_k}\right]\end{aligned}$$

$$\begin{aligned}
\Omega_1^{21}(k,i,n) &= -\Gamma^3 \left\{ T_n^I(k) \left[T_i^{\text{II}}(k) + \frac{T_i^I(k)}{\rho_k} - \frac{T_i(k)}{\rho_k^2} \right] \right. \\
&\quad \left. + T_n(k) \left[T_i^{\text{III}}(k) + \frac{T_i^{\text{II}}(k)}{\rho_k} - 2 \frac{T_i^I(k)}{\rho_k^2} + 2 \frac{T_i(k)}{\rho_k^3} \right] \right\} \\
\Omega_2^{21}(k,i,n) &= -\Gamma T_n(k) \left[T_i^I(k) + \frac{T_i(k)}{\rho_k} \right] \\
\Omega_3^{21}(k,i,n) &= -\Gamma [T_i^I(k) T_n(k) + T_i(k) T_n^I(k)] \\
\Omega_4^{21}(k,i,n) &= \Gamma T_i(k) \left[\frac{T_n(k)}{\rho_k} - T_n^I(k) \right] \\
\Omega_1^{22}(k,i,n) &= -\Gamma^2 \left\{ T_n(k) \left[T_i^{\text{II}}(k) + \frac{T_i^I(k)}{\rho_k} - \frac{T_i(k)}{\rho_k^2} \right] + \right. \\
&\quad \left. + T_n^I(k) \left[T_i^I(k) + \frac{T_i(k)}{\rho_k} \right] \right\} \\
\Omega_2^{22}(k,i,n) &= -\Gamma^2 \left\{ T_i(k) \left[\frac{T_n^I(k)}{\rho_k} - T_n^{\text{II}}(k) \right] + T_n(k) \right. \\
&\quad \left. \left[T_i^{\text{II}}(k) + \frac{T_i^I(k)}{\rho_k} - \frac{T_i(k)}{\rho_k^2} \right] \right\} \\
\Omega_3^{22}(k,i,n) &= -T_i(k) T_n(k) \\
\Omega_1^{31}(k,i,n) &= -\Gamma T_i^I(k) T_n(k) \\
\Omega_1^{32}(k,i,n) &= T_i(k) T_n^I(k) \\
\Omega_1^{33}(k,i,n) &= -\Gamma T_i(k) T_n^I(k) \\
\Omega_2^{33}(k,i,n) &= \Gamma T_n(k) \left[T_i^I(k) + \frac{T_i(k)}{\rho_k} \right]
\end{aligned} \tag{A.13a-t}$$