

In[603]:= `ClearAll["Global`*"]`

In[604]:= `(*Code for evaluation of volume integral which gives to electro-viscoelastic lift
Written by Akash Choudhary, 17/4/2020*)`

`(*shear and curvature in the flow eq.3.15*)`

$$\beta = 4(1 - 2s); \quad \gamma = -4k;$$

`(*Coefficients of the first reflection eq.3.36*)`

$$Us = \alpha + \frac{\gamma}{3} + Ha(Zp - Zw); \quad \Omega s = \frac{\beta}{2};$$

$$A1 = \frac{3}{4} \left(Us - \alpha - \frac{1}{3}\gamma - Ha(Zp - Zw) \right);$$

$$B1 = \frac{-1}{4} \left(Us - \alpha - \frac{3}{5}\gamma - Ha(Zp - Zw) \right) + \frac{1}{2} Ha Zp;$$

$$C1 = \Omega s - \frac{\beta}{2};$$

$$D1 = \frac{-5}{2}\beta; \quad EE1 = \frac{-1}{2}\beta; \quad F1 = \frac{\gamma}{3}; \quad G1 = \frac{-7}{120}\gamma;$$

$$H1 = \frac{1}{8}\gamma;$$

`(*First reflection of disturbance field eq.3.34*)`

$$Rvec = \{X, Y, Z\};$$

$$eX = \{1, 0, 0\};$$

$$eZ = \{0, 0, 1\};$$

$$v01 = \left((*A1 not accounted because stokeslet=0*) \right.$$

$$\left. + (B1) \left(-\frac{eX}{R^3} + \frac{3 X Rvec}{R^5} \right) + (*C1 not accounted because rotlet=0*) + D1 \left(\frac{Z X Rvec}{R^5} \right) + \right.$$

$$\left. EE1 \left(Z eX + X eZ - \frac{5 X Z Rvec}{R^2} \right) \frac{1}{R^5} + F1 \left(eX - \frac{2 Z^2 eX + X Rvec}{R^2} + \frac{2 X Z eZ}{R^2} \right) \frac{1}{R^3} + \right.$$

$$\left. G1 \left(eX - \frac{1}{R^2} (5 Z^2 eX + 10 X Z eZ + 13 X Rvec) + \frac{75 X Z^2 Rvec}{R^4} \right) \frac{1}{R^3} + \right.$$

$$\left. H1 \left(eX - \frac{1}{R^2} (5 Z^2 eX + 10 X Z eZ + 5 X Rvec) + \frac{35 Z^2 X Rvec}{R^4} \right) \frac{1}{R^5} \right) /. \{R \rightarrow \text{Sqrt}[X^2 + Y^2 + Z^2]\};$$

`(*Test field Eq.B2*)`

$$uT1 = \left(\frac{3}{4} \frac{ZX}{R^3} - \frac{3}{4} \frac{ZX}{R^5} \right) /. \{R \rightarrow \text{Sqrt}[X^2 + Y^2 + Z^2]\};$$

$$vT1 = \left(\frac{3}{4} \frac{ZY}{R^3} - \frac{3}{4} \frac{ZY}{R^5} \right) /. \{R \rightarrow \text{Sqrt}[X^2 + Y^2 + Z^2]\};$$

$$wT1 = \left(\frac{3}{4} \left(1 + \frac{Z^2}{R^2} \right) \frac{1}{R} + \frac{1}{4} \left(1 - \frac{3 Z^2}{R^2} \right) \frac{1}{R^3} \right) /. \{R \rightarrow \text{Sqrt}[X^2 + Y^2 + Z^2]\};$$

$$u1 = \{uT1, vT1, wT1\};$$

`(*Background flow field eq.3.39*)`

$$V = \{\alpha + \beta Z + \gamma Z^2 - Ha Zw - (Us), 0, 0\} // \text{Simplify};$$

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(*-----*)
(*Stress Tensors (Eq.3.19-3.20)*)
E1 = Grad[V, {X, Y, Z}] + Transpose[Grad[V, {X, Y, Z}]];
e1 = Grad[v01, {X, Y, Z}] + Transpose[Grad[v01, {X, Y, Z}]];

e2 = Table[v01[[1]] ∂x (e1[[i, j]]) + v01[[2]] ∂y (e1[[i, j]]) + v01[[3]] ∂z (e1[[i, j]]),
  {i, 1, 3}, {j, 1, 3}] + e1.Grad[v01, {X, Y, Z}] + Transpose[Grad[v01, {X, Y, Z}]].e1;
(*The matrix multiplication in mathematica is different from dot
  product using Einstein notation. In manuscript: e1.(∇v)T= e1ikvk,j;
  In mathematica: e1.(∇v). This maintains the consistency with Einstein's notation.*)
W1 = E1.e1 + e1.E1;
W2 = Table[V[[1]] ∂x (e1[[i, j]]) + V[[2]] ∂y (e1[[i, j]]) + V[[3]] ∂z (e1[[i, j]]),
  {i, 1, 3}, {j, 1, 3}] (*V.Transpose[Grad[e1, {X,Y,Z}]]*) +
  e1.Grad[V, {X, Y, Z}] + Transpose[Grad[V, {X, Y, Z}]].e1 +
  Table[v01[[1]] ∂x (E1[[i, j]]) + v01[[2]] ∂y (E1[[i, j]]) + v01[[3]] ∂z (E1[[i, j]]),
  {i, 1, 3}, {j, 1, 3}] (*v01.Transpose[Grad[E1, {X,Y,Z}]]*) +
  E1.Grad[v01, {X, Y, Z}] + Transpose[Grad[v01, {X, Y, Z}]].E1;
testGrad = (Grad[u1, {X, Y, Z}]) // Transpose;
(*Gradient of test field*)
(*-----*)

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In[623]=

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(*We now evaluate eq.3.41. Since the expression are quite lengthy,
we divide the integral in several parts.*)

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(*-----FIRST PART-----*)
(*Contribution due to W1*)

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In[625]:= one1 = Total[Total[Table[ W1[[i]] testGrad[[i]] , {i, 1, 3}]]];
one1psiINT =
  Integrate[one1 r^2 Sin[θ] /. {X → r Sin[θ] Cos[φ], Y → r Sin[θ] Sin[φ], Z → r Cos[θ]}] dφ;
one1thetaINT = Integrate[one1psiINT] dθ;
one1radINT = Integrate[Simplify[one1thetaINT, r > 0] dr;

(*Contribution due to e1.e1*)
e1e1 = e1.e1 // Simplify;
one2 = Total[Total[Table[ e1e1[[i]] testGrad[[i]] , {i, 1, 3}]]];
one2sph =
  Simplify[one2 /. {X → r Sin[θ] Cos[φ], Y → r Sin[θ] Sin[φ], Z → r Cos[θ]}, r > 0];
one2psiINT = Integrate[one2sph r^2 Sin[θ]] dφ;
one2thetaINT = Integrate[one2psiINT] dθ;
one2radINT = Integrate[Simplify[one2thetaINT, r > 0] dr;

(*-----*)

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In[635]=

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In[636]:= (*-----SECOND PART-----*)
(*Contribution due to W2*)
two1 = Total[Total[Table[ W2[[i]] testGrad[[i]], {i, 1, 3}]]];
two1angINT =
  Integrate[Integrate[two1 r^2 Sin[θ] /. {X → r Sin[θ] Cos[φ], Y → r Sin[θ] Sin[φ], Z → r Cos[θ]}] dφ] dθ;
two1radINT = Integrate[Simplify[two1angINT, r > 0] dr

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Out[638]= $-160 k \pi (-1 + 2 s)$

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In[639]:= (*Contribution due to e2-part1*)
e21 = Table[v01[[1]] ∂x (e1[[i, j]]) +
  v01[[2]] ∂y (e1[[i, j]]) + v01[[3]] ∂z (e1[[i, j]]), {i, 1, 3}, {j, 1, 3}];
two21 = Total[Total[Table[ e21[[i]] testGrad[[i]] , {i, 1, 3}]]];
two21sph =
  Simplify[two21 /. {X → r Sin[θ] Cos[φ], Y → r Sin[θ] Sin[φ], Z → r Cos[θ]}, r > 0];
two21angINT = Integrate[Integrate[two21sph r^2 Sin[θ]] dφ] dθ;
two21radINT = Integrate[Simplify[two21angINT, r > 0] dr

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Out[643]= $\frac{1}{7} \pi (-1 + 2 s) (32 k - 63 Ha Zp)$

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In[644]:= (*Contribution due to e2-part2*)
e22 = e1.Grad[v01, {X, Y, Z}];
two22 = Total[Total[Table[ e22[[i]] testGrad[[i]] , {i, 1, 3}]]];
two22sph =
  Simplify[two22 /. {X → r Sin[θ] Cos[φ], Y → r Sin[θ] Sin[φ], Z → r Cos[θ]}, r > 0];
two22psiINT = ∫02π ( two22sph r2 Sin[θ] ) dφ;
two22thetaINT = ∫0π ( two22psiINT ) dθ;
two22radINT = ∫1∞ Simplify[two22thetaINT, r > 0] dr
Out[649]= - $\frac{1}{7} \pi (-1 + 2 s) (16 k - 21 Ha Zp)$ 

In[650]:= (*Contribution due to e2-part3(i)*)
e23i = Transpose[Grad[v01, {X, Y, Z}]].(Grad[v01, {X, Y, Z}]);
two23i = Total[Total[Table[ e23i[[i]] testGrad[[i]] , {i, 1, 3}]]];
two23sph =
  Simplify[two23i /. {X → r Sin[θ] Cos[φ], Y → r Sin[θ] Sin[φ], Z → r Cos[θ]}, r > 0];
two23psiINTi = ∫02π ( two23sph r2 Sin[θ] ) dφ;
two23thetaINTi = ∫0π ( two23psiINTi ) dθ;
two23radINTi = ∫1∞ Simplify[two23thetaINTi, r > 0] dr
Out[655]= - $\frac{1}{7} \pi (-1 + 2 s) (16 k - 21 Ha Zp)$ 

In[656]:= (*Contribution due to e2-part3(ii)*)
e23ii = Transpose[Grad[v01, {X, Y, Z}]].Transpose[(Grad[v01, {X, Y, Z}])];
two23ii = Total[Total[Table[ e23ii[[i]] testGrad[[i]] , {i, 1, 3}]]];
two23iisph =
  Simplify[two23ii /. {X → r Sin[θ] Cos[φ], Y → r Sin[θ] Sin[φ], Z → r Cos[θ]}, r > 0];
two23psiINTii = ∫02π ( two23iisph r2 Sin[θ] ) dφ;
two23thetaINTii = ∫0π ( two23psiINTii ) dθ;
two23radINTii = ∫1∞ Simplify[two23thetaINTii, r > 0] dr
Out[661]= -3 Ha π (-1 + 2 s) Zp

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(*All terms multiplied by -1 because the integral(eq.3.41) has -
1 coefficient in front of it. Here the second part is multiplied with δ ,
which is consistent with eq. 3.19*)

TOTAL = - (one2radINT + one1radINT) -

δ (two1radINT + two21radINT + two22radINT + two23radINTi + two23radINTii);

(*Components from electrophoresis: Electro-Viscoelastic migration*)

EVM = beta * HaZp * Coefficient[$\frac{\text{TOTAL}}{\beta}$, Ha Zp] // Simplify

(*Remaining terms: Ho and Leal (1974), Viscoelastic migration*)

VM = beta * gamma * $\frac{\text{TOTAL} - (\text{Ha Zp}) \text{Coefficient}[\text{TOTAL}, \text{Ha Zp}]}{\beta \gamma}$ // Simplify // Factor

$$\text{Out}[663]= -\frac{3}{2} \text{beta HaZp } \pi (1 + \delta)$$

$$\text{Out}[664]= \frac{10}{3} \text{beta gamma } \pi (1 + 3 \delta)$$