

The Dirichlet-to-Neumann map for an annular channel

Matthew Durey, Paul A. Milewski and Zhan Wang

December 30, 2019

We compute the Dirichlet-to-Neumann map for ϕ in an annular cavity, Ω , using a Domain Decomposition method similar to that implemented for the corral geometry. We decompose $\Omega = \Omega_S \cup \Omega_D$, where

$$\begin{aligned}\Omega_S &= \{(r, \theta, z) : r < r_\infty, \theta \in [0, 2\pi), z \in (-h_s, 0)\}, \\ \Omega_D &= \{(r, \theta, z) : r_1 < r < r_2, \theta \in [0, 2\pi), z \in (-h_d, -h_s)\},\end{aligned}$$

with $0 < r_1 < r_2 < r_\infty < \infty$ and $0 < h_s < h_d$. We consider $\Delta\phi + \phi_{zz} = 0$ in Ω , where Δ is the horizontal Laplacian operator. For a given function $a(r, \theta)$, the boundary conditions for ϕ are

$$\phi = a \quad \text{on} \quad z = 0, \quad r < r_\infty, \quad (1a)$$

$$\phi = 0 \quad \text{on} \quad r = r_\infty, \quad z \in (-h_s, 0), \quad (1b)$$

$$\partial_r \phi = 0 \quad \text{on} \quad r = r_1, \quad z \in (-h_d, -h_s), \quad (1c)$$

$$\partial_r \phi = 0 \quad \text{on} \quad r = r_2, \quad z \in (-h_d, -h_s), \quad (1d)$$

$$\partial_z \phi = 0 \quad \text{on} \quad z = -h_d, \quad r \in (r_1, r_2), \quad (1e)$$

$$\partial_z \phi = 0 \quad \text{on} \quad z = -h_s, \quad r \notin (r_1, r_2), \quad (1f)$$

where we assume a bounded solution in the limit $r \rightarrow 0$. This configuration is depicted in figure 1.

We then define ϕ^S and ϕ^D such that

$$\phi(r, \theta, z) = \begin{cases} \phi^S(r, \theta, z), & (r, \theta, z) \in \Omega_S, \\ \phi^D(r, \theta, z), & (r, \theta, z) \in \Omega_D. \end{cases}$$

Both ϕ^S and ϕ^D satisfy Laplace's equation in their respective domains, equipped with boundary conditions consistent with (1). The aim is to solve for ϕ given the Dirichlet data $\phi|_{z=0} = a$, from which we determine the corresponding Neumann data, $\phi_z|_{z=0}$. To solve for ϕ^S and ϕ^D concurrently, we introduce the unknown functions $b^S(r, \theta)$ and $b^D(r, \theta)$, satisfying

$$\phi^S = b^S \quad \text{and} \quad \phi^D = b^D \quad \text{on} \quad z = -h_s.$$

The functions b^S and b^D are chosen to be consistent with the fluid flow, specifically

$$\begin{aligned}b^S &= b^D & \text{on} \quad z = -h_s, \quad r_1 < r < r_2, \\ \partial_z \phi^S &= \partial_z \phi^D & \text{on} \quad z = -h_s, \quad r_1 < r < r_2, \\ \partial_z \phi^S &= 0 & \text{on} \quad z = -h_s, \quad r \notin (r_1, r_2).\end{aligned}$$

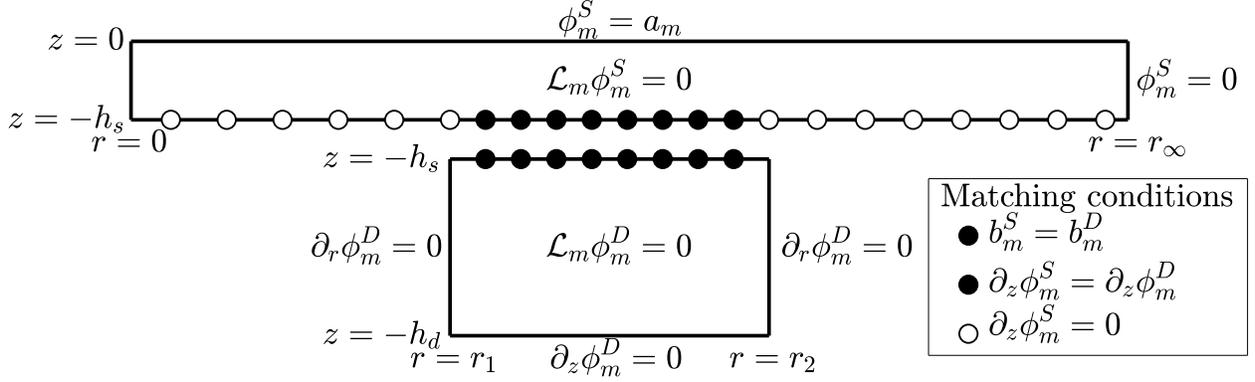


Figure 1: Cross-sectional schematic diagram for the Domain Decomposition method. Circles denote the N_S radial collocation points, of which N_D points (black circles) lie in the deep region. The differential operator is $\mathcal{L}_m = \partial_{rr} + r^{-1}\partial_r + \partial_{zz} - (m/r)^2$. At $r = 0$, we seek a bounded solution.

We proceed by expanding ϕ^S , ϕ^D , a , b^S , and b^D into Fourier angular modes, for example $\phi^S(r, \theta, z) = \sum_{m=-\infty}^{\infty} \phi_m^S(r, z)e^{im\theta}$, where $i^2 = -1$. As ϕ^S and ϕ^D are both harmonic functions, it is necessary to solve

$$\begin{aligned} \mathcal{L}_m \phi_m^S &= 0, & \text{for } (r, z) \in [0, r_\infty) \times (-h_s, 0), \\ \mathcal{L}_m \phi_m^D &= 0, & \text{for } (r, z) \in (r_1, r_2) \times (-h_d, -h_s), \end{aligned}$$

where $\mathcal{L}_m = \partial_{rr} + r^{-1}\partial_r + \partial_{zz} - (m/r)^2$ is Laplace's operator for angular mode m . As depicted in figure 1, the boundary conditions for the shallow region are $\phi_m^S = 0$ on $r = r_\infty$, $\phi_m^S = a_m$ on $z = 0$, $\phi_m^S = b_m^S$ on $z = -h_s$, with ϕ_m^S bounded as $r \rightarrow 0$. Similarly, we require $\partial_r \phi_m^D = 0$ on $r = r_1$, $\partial_r \phi_m^D = 0$ on $r = r_2$, $\phi_m^D = b_m^D$ on $z = -h_s$, $\partial_z \phi_m^D = 0$ on $z = -h_d$, and boundedness of ϕ_m^D as $r \rightarrow 0$.

We first solve for ϕ_m^S and ϕ_m^D before determining b_m^S and b_m^D according to the matching conditions. To solve $\mathcal{L}_m \phi_m^S = 0$ with respect to the radial boundary conditions, we employ the Hankel Transform $\phi_m^S(r, z) = \sum_{p=1}^{\infty} \phi_{mp}^S(z) J_m(k_{mp}r)$ (similarly for b_m^S and a_m), where J_m is the Bessel function of the first kind of order m . The distinct wavenumbers $k_{mp} > 0$ satisfy the Dirichlet boundary condition (1a) at $r = r_\infty$, specifically $J_m(k_{mp}r_\infty) = 0$. The analytic solution for $\phi_m^S(r, z)$ is then

$$\phi_m^S(r, z) = \sum_{p=1}^{\infty} \left[a_{mp} \frac{\sinh(k_{mp}(z + h_s))}{\sinh(k_{mp}h_s)} - b_{mp}^S \frac{\sinh(k_{mp}z)}{\sinh(k_{mp}h_s)} \right] J_m(k_{mp}r). \quad (2)$$

For solving for ϕ_m^D , we now modify the method adopted for the circular corral since one must also consider the Bessel function Y_m of the second kind of order m (as $r_1 > 0$). Specifically, we define the family of cylinder functions $\mathcal{C}_m(\varrho, \vartheta) = J_m(\varrho) \cos(\pi\vartheta) + Y_m(\varrho) \sin(\pi\vartheta)$ for $\varrho > 0$ and $\vartheta \in (0, 1)$. We express

$$\phi_m^D(r, z) = \sum_{p=1}^{\infty} \phi_{mp}^D(z) \mathcal{C}_m(\xi_{mp}r, \vartheta_{mp}),$$

where the pair $(\xi_{mp}, \vartheta_{mp})$ is chosen to satisfy the radial boundary conditions (1c)–(1d), namely

$$J'_m(\xi_{mp}r_1) \cos(\vartheta_{mp}\pi) + Y'_m(\xi_{mp}r_1) \sin(\vartheta_{mp}\pi) = 0, \quad (3a)$$

$$J'_m(\xi_{mp}r_2) \cos(\vartheta_{mp}\pi) + Y'_m(\xi_{mp}r_2) \sin(\vartheta_{mp}\pi) = 0. \quad (3b)$$

We first note that the pair $(\xi_{01}, \vartheta_{01}) = (0, 0)$ corresponds to the unit eigenfunction. To compute the remaining pairs $(\xi_{mp}, \vartheta_{mp})$ for $\xi_{mp} > 0$, we eliminate ϑ_{mp} from (3) to obtain a single equation for ξ_{mp} given r_1 and r_2 , namely

$$J'_m(\xi_{mp}r_1)Y'_m(\xi_{mp}r_2) - J'_m(\xi_{mp}r_2)Y'_m(\xi_{mp}r_1) = 0.$$

The discrete values of ξ_{mp} may be computed numerically, where we consider the order $0 \leq \xi_{m1} < \xi_{m2} < \dots$. Given $\xi_{mp} > 0$, we then use (3a) to determine $\vartheta_{mp} \in (0, 1)$, namely

$$\vartheta_{mp} = -\frac{1}{\pi} \arctan \left(\frac{J'_m(\xi_{mp}r_1)}{Y'_m(\xi_{mp}r_1)} \right) \pmod{1}.$$

Through consideration of the boundary conditions for ϕ_{mp}^D , we then obtain the well-known DtN map for finite depth, namely

$$\partial_z \phi_{mp}^D(-h_s) = b_{mp}^D \xi_{mp} \tanh(\xi_{mp}(h_d - h_s)).$$

Hence,

$$\partial_z \phi_m^D(r, -h_s) = \sum_{p=1}^{\infty} b_{mp}^D \xi_{mp} \tanh(\xi_{mp}(h_d - h_s)) \mathcal{C}_m(\xi_{mp}r, \vartheta_{mp}). \quad (4)$$

To match the velocity potential along $z = -h_s$ for each angular mode m , we utilise N_S radial collocation points ρ_j , where $0 \leq \rho_1 < \rho_2 < \dots < \rho_{N_S} < r_\infty$, which are defined similarly to the main text. To satisfy the velocity continuity between the domains Ω_S and Ω_D , as well as the no-flux condition through the base of the corral (see equation (1f)), at each radial collocation point, ρ_j , we require

$$b_m^S = b_m^D, \quad \rho_j \in (r_1, r_2), \quad (5a)$$

$$\partial_z \phi_m^S = \partial_z \phi_m^D, \quad \rho_j \in (r_1, r_2), \quad z = -h_s, \quad (5b)$$

$$\partial_z \phi_m^S = 0, \quad \rho_j \notin (r_1, r_2), \quad z = -h_s. \quad (5c)$$

Following a similar procedure to the corral problem, $N_D < N_S$ collocation points satisfy $\rho_j \in (r_1, r_2)$. For a well-posed problem, we must similarly truncate the wavenumbers k_{mp} and ξ_{mp} to $p \leq N_S$ and $p \leq N_D$ in the shallow and deep regions, respectively.

To satisfy conditions (5b)–(5c), we evaluate (2)–(4) at the collocation points, yielding a system of N_S equations for $b_{m1}^S, \dots, b_{mN_S}^S$ and $b_{m1}^D, \dots, b_{mN_D}^D$:

$$\begin{aligned} \sum_{p=1}^{N_S} (a_{mp} - b_{mp}^S \cosh(k_{mp}h_s)) \frac{k_{mp} J_m(k_{mp}\rho_j)}{\sinh(k_{mp}h_s)} \\ = \begin{cases} \sum_{p=1}^{N_D} b_{mp}^D \xi_{mp} \tanh(\xi_{mp}(h_d - h_s)) \mathcal{C}_m(\xi_{mp}\rho_j, \vartheta_{mp}), & \rho_j \in (r_1, r_2), \\ 0, & \rho_j \notin (r_1, r_2). \end{cases} \end{aligned} \quad (6)$$

To close the system, the continuity condition (5a) gives

$$\sum_{p=1}^{N_S} b_{mp}^S J_m(k_{mp}\rho_j) = \sum_{p=1}^{N_D} b_{mp}^D \mathcal{C}_m(\xi_{mp}\rho_j, \vartheta_{mp}), \quad \forall \rho_j \in (r_1, r_2). \quad (7)$$

The system of equations (6)–(7) may be expressed as a system of size $(N_S + N_D)$ and inverted for b_{mp}^S and b_{mp}^D . Equation (2) then determines the Dirichlet-to-Neumann map

$$\partial_z \phi_{mp}^S(0) = k_{mp} (a_{mp} \coth(k_{mp}h_s) - b_{mp}^S \operatorname{cosech}(k_{mp}h_s)).$$