

Supplementary Figures

Design of an Ankle Exoskeleton with Twisted String Actuation for Running Assistance

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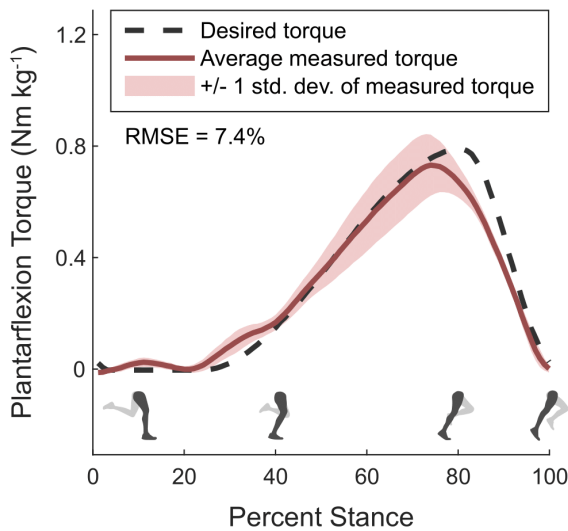


Figure S1. Ankle torque tracking during the final 20 strides prior to transmission failure. The reduction in peak torque and increase in torque tracking error during the push-off phase of stance (80% to 100% of stance) indicate that transmission wear led to higher transmission losses, motor saturation, and lower power production at the ankle joint.