

## A Maximum Likelihood Estimators of Selected State-Dependent Distributions

Without loss of generality, we provide the MLE for the distribution parameters of the  $u$ -th latent state in the  $m$ -th iteration. To simplify the notation, we let  $\hat{z}_{ijl,u}^{(m)} = \mathbb{E}(\mathbb{1}_{\{Z_{ijl}=u\}} | \mathbf{Y}^*, \mathbf{T}^*, \Phi^{(m-1)})$ .

- Gamma( $k, \theta$ ) (shape-scale parametrization)

$$k^{(m)} = k \quad \text{such that} \quad \sum_{i,j,l} \hat{z}_{ijl,u}^{(m)} \left\{ \log \Gamma(k) + k \log(\theta^{(m-1)}) - (k-1) \log(y_{ijl}) + \frac{1}{\theta^{(m-1)}} y_{ijl} \right\} = 0$$

$$\theta^{(m)} = \frac{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)} y_{ijl}}{k^{(m)} \sum_{i,j,l} \hat{z}_{ijl,u}^{(m)}}$$

- Laplace( $\mu, \theta$ )

$$\mu^{(m)} = \text{weighted median of } y_{ijl} \text{ with weights } \hat{z}_{ijl,u}^{(m)}$$

$$\theta^{(m)} = \frac{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)} |y_{ijl} - \mu^{(m)}|}{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)}}$$

- Log-Normal( $\mu, \sigma^2$ )

$$\mu^{(m)} = \frac{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)} \log(y_{ijl})}{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)}}$$

$$(\sigma^2)^{(m)} = \frac{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)} (\log(y_{ijl}) - \mu^{(m)})^2}{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)}}$$

- Normal( $\mu, \sigma^2$ )

$$\mu^{(m)} = \frac{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)} y_{ijl}}{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)}}$$

$$(\sigma^2)^{(m)} = \frac{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)} (y_{ijl} - \mu^{(m)})^2}{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)}}$$

- von Mises( $\mu, \kappa$ )

$$\mu^{(m)} = \arctan \left( \frac{\sum_{j,k} \hat{z}_{ijl,u}^{(m)} \sin(y_{ijl})}{\sum_{j,k} \hat{z}_{ijl,u}^{(m)} \cos(y_{ijl})} \right)$$

$$\kappa^{(m)} = \kappa \quad \text{such that} \quad A(\kappa) = \frac{I_1(\kappa)}{I_0(\kappa)} = \frac{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)} \cos(y_{ijl} - \mu^{(m)})}{\sum_{i,j,l} \hat{z}_{ijl,u}^{(m)}}$$

where  $I_0(\kappa)$  and  $I_1(\kappa)$  are the modified Bessel function of the first kind of orders 0 and 1 respectively.

**B Controlled Study: Anomaly Indices from Individual-Specific Models with Fewer States**

Table B1: UAH-DriveSet: Anomaly index in each dimension of telematics observations, computed from individual-specific CTHMMs with 5 states for each driver and averaged over 100 random initializations. Note: S stands for Secondary Road and M stands for Motorway; Z and Y are longitudinal and lateral accelerations, respectively.

Driver	Trip	Y_KF	Z_KF	Speed
D1	S-Normal 1	0.0025	0.0014	0.0000
	S-Normal 2	0.0027	0.0032	0.0000
	S-Aggressive	0.0112	<b>0.0104</b>	0.0000
	S-Drowsy	0.0043	<b>0.0083</b>	0.0000
	M-Normal	0.0135	0.0020	0.0002
	M-Aggressive	0.0032	0.0079	0.0010
	M-Drowsy	0.0013	0.0034	0.0000
	D2	S-Normal 1	0.0031	0.0015
S-Normal 2		0.0047	0.0000	0.0000
S-Aggressive		0.0016	<b>0.0317</b>	0.0000
S-Drowsy		0.0258	0.0078	0.0000
M-Normal		0.0063	0.0019	0.0019
M-Aggressive		0.0129	<b>0.0158</b>	0.0108
M-Drowsy		0.0180	0.0043	0.0001
D3		S-Normal 1	0.0065	0.0029
	S-Normal 2	0.0121	0.0105	0.0000
	S-Aggressive	0.0114	<b>0.0436</b>	0.0000
	S-Drowsy	0.0114	0.0062	0.0000
	M-Normal	0.0067	0.0038	0.0119
	M-Aggressive	0.0103	<b>0.0305</b>	0.0404
	M-Drowsy	0.0150	0.0010	0.0000
	D4	S-Normal 1	0.0056	0.0021
S-Normal 2		0.0103	0.0022	0.0000
S-Aggressive		0.0112	<b>0.0168</b>	0.0000
S-Drowsy		0.0235	0.0059	0.0000
M-Normal		0.0035	0.0030	0.0070
M-Aggressive		0.0242	<b>0.0275</b>	0.0000
M-Drowsy		0.0107	0.0019	0.0000
D5		S-Normal 1	0.0000	0.0000
	S-Normal 2	0.0000	0.0000	0.0044
	S-Aggressive	0.0067	<b>0.0116</b>	0.0000
	S-Drowsy	0.0040	0.0013	0.0000
	M-Normal	0.0033	0.0030	0.0011
	M-Aggressive	0.0088	<b>0.0138</b>	0.0000
	M-Drowsy	0.0046	0.0009	0.0000

Table B2: UAH-DriveSet: Anomaly index in each dimension of telematics observations, computed from individual-specific CTHMMs with 10 states for each driver and averaged over 100 random initializations. Note: S stands for Secondary Road and M stands for Motorway; Z and Y are longitudinal and lateral accelerations, respectively.

Driver	Trip	Y_KF	Z_KF	Speed
D1	S-Normal 1	0.0076	0.0032	0.0000
	S-Normal 2	0.0033	0.0000	0.0000
	S-Aggressive	0.0064	<i>0.0056</i>	0.0000
	S-Drowsy	0.0053	<b>0.0057</b>	0.0000
	M-Normal	0.0023	0.0004	0.0010
	M-Aggressive	0.0042	<b>0.0064</b>	0.0039
	M-Drowsy	0.0018	0.0032	0.0000
D2	S-Normal 1	0.0026	0.0003	0.0000
	S-Normal 2	0.0053	0.0003	0.0000
	S-Aggressive	0.0006	<b>0.0174</b>	0.0000
	S-Drowsy	0.0245	0.0051	0.0000
	M-Normal	0.0051	0.0022	0.0019
	M-Aggressive	0.0104	<b>0.0136</b>	0.0060
	M-Drowsy	0.0151	0.0038	0.0000
D3	S-Normal 1	0.0049	0.0028	0.0000
	S-Normal 2	0.0073	0.0082	0.0000
	S-Aggressive	0.0092	<b>0.0301</b>	0.0000
	S-Drowsy	0.0073	0.0043	0.0000
	M-Normal	0.0062	0.0017	0.0016
	M-Aggressive	0.0078	<b>0.0283</b>	0.0138
	M-Drowsy	0.0083	0.0008	0.0000
D4	S-Normal 1	0.0046	0.0028	0.0000
	S-Normal 2	0.0068	0.0023	0.0000
	S-Aggressive	0.0082	<b>0.0145</b>	0.0000
	S-Drowsy	0.0184	0.0054	0.0000
	M-Normal	0.0023	0.0015	0.0028
	M-Aggressive	0.0112	<b>0.0239</b>	0.0002
	M-Drowsy	0.0062	0.0005	0.0000
D5	S-Normal 1	0.0001	0.0003	0.0000
	S-Normal 2	0.0030	0.0027	0.0046
	S-Aggressive	0.0056	<b>0.0147</b>	0.0000
	S-Drowsy	0.0042	0.0019	0.0000
	M-Normal	0.0009	0.0025	0.0010
	M-Aggressive	0.0105	<b>0.0112</b>	0.0000
	M-Drowsy	0.0056	0.0011	0.0000

Table B3: UAH-DriveSet: Anomaly index in each dimension of telematics observations, computed from individual-specific CTHMMs with 15 states for each driver and averaged over 100 random initializations. Note: S stands for Secondary Road and M stands for Motorway; Z and Y are longitudinal and lateral accelerations, respectively.

Driver	Trip	Y_KF	Z_KF	Speed
D1	S-Normal 1	0.0105	0.0043	0.0000
	S-Normal 2	0.0055	0.0015	0.0000
	S-Aggressive	0.0085	<i>0.0060</i>	0.0000
	S-Drowsy	0.0090	<b>0.0062</b>	0.0000
	M-Normal	0.0033	0.0012	0.0001
	M-Aggressive	0.0049	<b>0.0092</b>	0.0027
	M-Drowsy	0.0021	0.0038	0.0000
D2	S-Normal 1	0.0022	0.0006	0.0000
	S-Normal 2	0.0043	0.0002	0.0000
	S-Aggressive	0.0017	<b>0.0197</b>	0.0003
	S-Drowsy	0.0226	0.0048	0.0000
	M-Normal	0.0032	0.0019	0.0011
	M-Aggressive	0.0082	<b>0.0163</b>	0.0019
	M-Drowsy	0.0146	0.0041	0.0000
D3	S-Normal 1	0.0047	0.0021	0.0000
	S-Normal 2	0.0072	0.0056	0.0000
	S-Aggressive	0.0099	<b>0.0216</b>	0.0000
	S-Drowsy	0.0075	0.0040	0.0000
	M-Normal	0.0057	0.0020	0.0049
	M-Aggressive	0.0057	<b>0.0225</b>	0.0004
	M-Drowsy	0.0080	0.0006	0.0000
D4	S-Normal 1	0.0046	0.0031	0.0000
	S-Normal 2	0.0083	0.0015	0.0000
	S-Aggressive	0.0098	<b>0.0143</b>	0.0000
	S-Drowsy	0.0169	0.0032	0.0000
	M-Normal	0.0022	0.0020	0.0021
	M-Aggressive	0.0146	<b>0.0187</b>	0.0002
	M-Drowsy	0.0059	0.0011	0.0000
D5	S-Normal 1	0.0002	0.0009	0.0000
	S-Normal 2	0.0022	0.0022	0.0043
	S-Aggressive	0.0065	<b>0.0128</b>	0.0000
	S-Drowsy	0.0056	0.0027	0.0000
	M-Normal	0.0011	0.0031	0.0005
	M-Aggressive	0.0102	<b>0.0072</b>	0.0000
	M-Drowsy	0.0059	0.0011	0.0000

### C Real-Data Analysis: Summaries of Logistic Models from Individual-Specific Models

Table C1: Model summary of logistic GLMs, with raw or normalized anomaly indices as covariates. Note: x1, x2 and x3 denote indices for speed, longitudinal and lateral accelerations respectively.

	<b>Estimate</b>	<b>Std. Error</b>	<b>z value</b>	<b>p value</b>	
(Intercept)	-3.395	0.137	-24.825	< 2e-16	***
x1	-23.146	20.594	-1.124	0.261	
x2	51.219	8.630	5.935	2.93e-09	***
x3	63.827	9.416	6.779	1.21e-11	***

	<b>Estimate</b>	<b>Std. Error</b>	<b>z value</b>	<b>p value</b>	
(Intercept)	-4.316	0.206	-20.961	<2e-16	***
norm x1	0.309	0.557	0.555	0.579	
norm x2	2.770	0.298	9.305	<2e-16	***
norm x3	2.903	0.292	9.957	<2e-16	***

Significance codes: 0 '\*\*\*', 0.001 '\*\*', 0.01 '\*', 0.05 '.', 0.1 ' ', 1

Table C2: Feature importance of logistic XGBoost, with raw or normalized anomaly as covariates. Note: x1, x2 and x3 denote indices for speed, longitudinal and lateral accelerations respectively.

	<b>Gain</b>	<b>Cover</b>	<b>Frequency</b>
x3	0.557	0.492	0.447
x2	0.382	0.401	0.392
x1	0.061	0.106	0.161

	<b>Gain</b>	<b>Cover</b>	<b>Frequency</b>
norm x3	0.537	0.530	0.389
norm x2	0.430	0.414	0.465
norm x1	0.033	0.056	0.146

## D Real-Data Analysis: Pooled Model Analysis with Alternative Training Sets

Table D1: Comparison of anomaly indices (%) in each telematics response dimension for claimed and no-claim rentals, computed from pooled CTHMMs trained on samples with 0% and 100% claim rates.

	<b>Trip-Basis</b>			
	<b>0%</b>		<b>100%</b>	
	claimed	no claim	claimed	no claim
speed	0.0716	0.0995	0.0462	0.0523
longitudinal	0.5405	0.6549	0.2473	0.3008
lateral	0.3048	0.3517	0.2178	0.2384

	<b>Rental-Basis</b>			
	<b>0%</b>		<b>100%</b>	
	claimed	no claim	claimed	no claim
<b>Average</b>				
speed	0.0713	0.0968	0.0433	0.0559
longitudinal	0.6246	0.8882	0.2680	0.3936
lateral	0.3190	0.3801	0.2219	0.2711
<b>Maximum</b>				
speed	32.3730	17.2720	25.2180	12.0900
longitudinal	35.8500	20.8000	28.2700	14.8470
lateral	33.9200	18.8010	27.2260	13.9027

Table D2: 5-fold cross-validation ROC-AUC of logistic GLMs with different sets of covariates. Set 1: maximum anomaly indices, Set 2: right tail of the anomaly index empirical distribution, Set 3: right tail and the number of trips as an offset. Note: first column indicates the claim rate of the training set the pooled CTHMM is fitted on.

	<b>Covariate Sets</b>		
	<b>Set 1</b>	<b>Set 2</b>	<b>Set 3</b>
0% Training Set	0.6905	0.7509	0.7861
100% Training Set	0.6962	0.7286	0.7669